

Accurate Approximate Diagnosability of Stochastic Systems

Nathalie Bertrand¹, Serge Haddad², Engel Lefauchaux^{1,2}

1 Inria, France

2 LSV, ENS Cachan & CNRS & Inria, France

GdT Vasco-Mexico, March 9th 2016

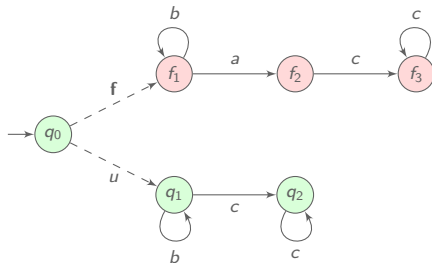


Diagnosis Framework

LTS: Labelled transition system.

Diagnoser: must tell whether a fault f occurred, based on observations.

Convergence hypothesis: no infinite sequence of unobservable events.

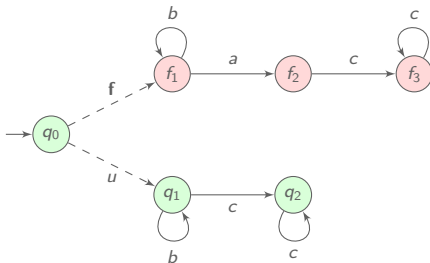


Diagnosis Framework

LTS: Labelled transition system.

Diagnoser: must tell whether a fault \mathbf{f} occurred, based on observations.

Convergence hypothesis: no infinite sequence of unobservable events.



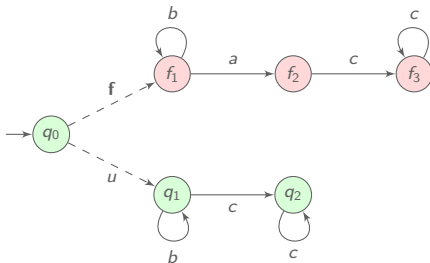
A run $\rho = q_0 \xrightarrow{u} q_1 \xrightarrow{c} q_2$ has an observation sequence $\mathcal{P}(\rho) = c$.

Diagnosis Framework

LTS: Labelled transition system.

Diagnoser: must tell whether a fault **f** occurred, based on observations.

Convergence hypothesis: no infinite sequence of unobservable events.



A run $\rho = q_0 \xrightarrow{u} q_1 \xrightarrow{c} q_2$ has an observation sequence $\mathcal{P}(\rho) = c$.

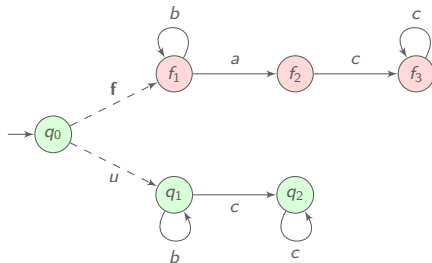
X ac is surely faulty as $\mathcal{P}^{-1}(ac) = \{q_0 \xrightarrow{f} f_1 \xrightarrow{a} f_2 \xrightarrow{c} f_3\}$.

Diagnosis Framework

LTS: Labelled transition system.

Diagnoser: must tell whether a fault **f** occurred, based on observations.

Convergence hypothesis: no infinite sequence of unobservable events.



A run $\rho = q_0 \xrightarrow{u} q_1 \xrightarrow{c} q_2$ has an observation sequence $\mathcal{P}(\rho) = c$.

X ac is surely faulty as $\mathcal{P}^{-1}(ac) = \{q_0 \xrightarrow{f} f_1 \xrightarrow{a} f_2 \xrightarrow{c} f_3\}$.

? b is ambiguous as $\mathcal{P}^{-1}(b) = \{q_0 \xrightarrow{f} f_1 \xrightarrow{b} f_1, q_0 \xrightarrow{u} q_1 \xrightarrow{b} q_1\}$.

Diagnosis Problems

Diagnoser requirements:

- ▶ **Soundness:** if a fault is claimed, a fault occurred.
- ▶ **Reactivity:** every fault will be detected.

Diagnosis Problems

Diagnoser requirements:

- ▶ **Soundness:** if a fault is claimed, a fault occurred.
- ▶ **Reactivity:** every fault will be detected.

A decision problem (*diagnosability*): does there exist a diagnoser?

A synthesis problem: how to build a diagnoser?

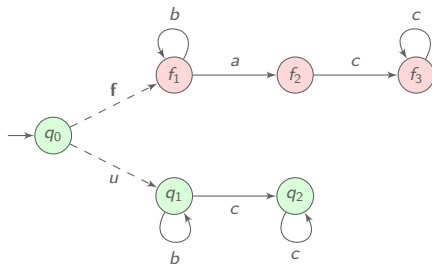
Diagnosis Problems

Diagnoser requirements:

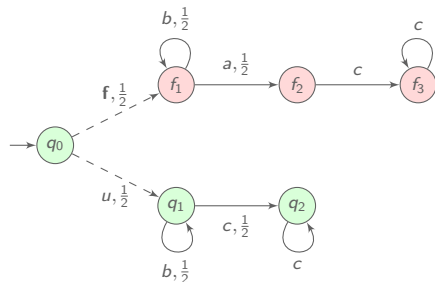
- ▶ **Soundness:** if a fault is claimed, a fault occurred.
- ▶ **Reactivity:** every fault will be detected.

A decision problem (*diagnosability*): does there exist a diagnoser?

A synthesis problem: how to build a diagnoser?



A sound but not reactive diagnoser : claiming a fault when a occurs.

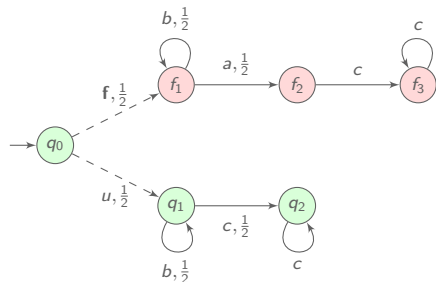


[TT05] Thorsley and Teneketzis

Diagnosability of stochastic discrete-event systems, IEEE TAC, 2005.

Diagnosis of Probabilistic Systems

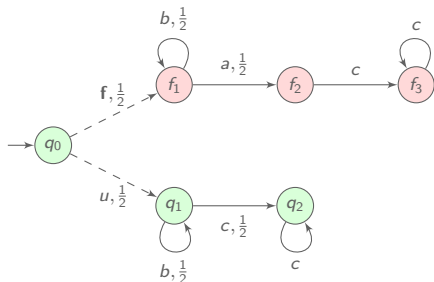
[TT05]



b^n ambiguous but...

[TT05] Thorsley and Teneketzis

Diagnosability of stochastic discrete-event systems, IEEE TAC, 2005.

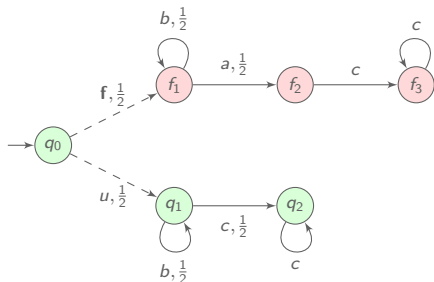


b^n ambiguous but...

$$\lim_{n \rightarrow \infty} \mathbb{P}(fb^n) = 0$$

[TT05] Thorsley and Teneketzis

Diagnosability of stochastic discrete-event systems, IEEE TAC, 2005.



f^n ambiguous but...

$$\lim_{n \rightarrow \infty} \mathbb{P}(f b^n) = 0$$

How to adapt soundness and reactivity?

[TT05] Thorsley and Teneketzis

Diagnosability of stochastic discrete-event systems, IEEE TAC, 2005.

Exact Diagnosis

[BHL14]

An *exact diagnoser* fulfills

- ▶ **Soundness**: if a fault is claimed, a fault happened.

[BHL14] Bertrand, Haddad, Lefauchaux

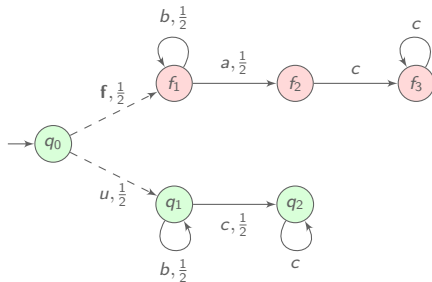
Foundation of Diagnosis and Predictability in Probabilistic Systems, FSTTCS'14.

Exact Diagnosis

[BHL14]

An *exact diagnoser* fulfills

- ▶ **Soundness**: if a fault is claimed, a fault happened.
- ▶ **Reactivity**: the diagnoser will provide information almost surely.



Exactly diagnosable.

[BHL14] Bertrand, Haddad, Lefaucheu

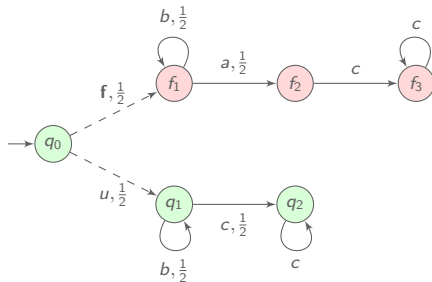
Foundation of Diagnosis and Predictability in Probabilistic Systems, FSTTCS'14.

Exact Diagnosis

[BHL14]

An *exact diagnoser* fulfills

- ▶ **Soundness**: if a fault is claimed, a fault happened.
- ▶ **Reactivity**: the diagnoser will provide information almost surely.



Exactly diagnosable.

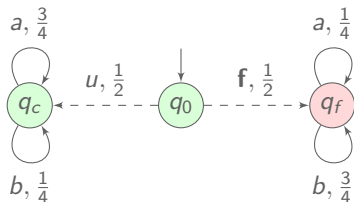
Exact diagnosability is PSPACE-complete.

Also studied : exact prediction and prediagnosis.

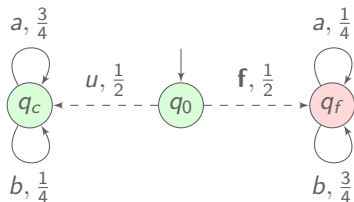
[BHL14] Bertrand, Haddad, Lefaucheu

Foundation of Diagnosis and Predictability in Probabilistic Systems, FSTTCS'14.

Exact Diagnosis versus Approximate Diagnosis

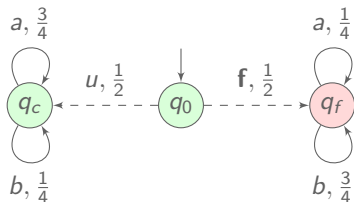


Exact Diagnosis versus Approximate Diagnosis



Not exactly diagnosable

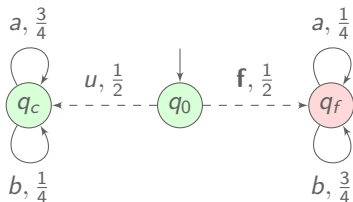
Exact Diagnosis versus Approximate Diagnosis



Not exactly diagnosable

However a high proportion of b implies a highly probable faulty run.

Exact Diagnosis versus Approximate Diagnosis



Not exactly diagnosable

However a high proportion of b implies a highly probable faulty run.

Relaxed Soundness: if a fault is claimed the probability of error is small.

Outline

Specification of Approximate Diagnosis

AA-diagnosis is Easy

Other Approximate Diagnoses are Hard

Outline

Specification of Approximate Diagnosis

AA-diagnosis is Easy

Other Approximate Diagnoses are Hard

Proportion of Correct Runs

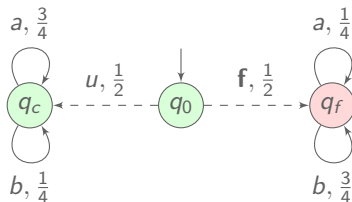
Given an observation sequence $\sigma \in \Sigma_o^*$,

$$\text{CorP}(\sigma) = \frac{\mathbb{P}(\{\pi^{-1}(\sigma) \cap \text{correct}\})}{\mathbb{P}(\{\pi^{-1}(\sigma)\})}$$

Proportion of Correct Runs

Given an observation sequence $\sigma \in \Sigma_o^*$,

$$\text{CorP}(\sigma) = \frac{\mathbb{P}(\{\pi^{-1}(\sigma) \cap \text{correct}\})}{\mathbb{P}(\{\pi^{-1}(\sigma)\})}$$

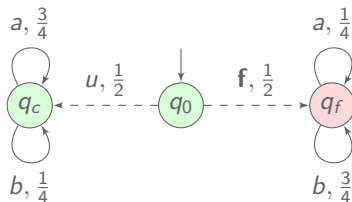


$$\text{CorP}(a) = 3/4,$$

Proportion of Correct Runs

Given an observation sequence $\sigma \in \Sigma_o^*$,

$$\text{CorP}(\sigma) = \frac{\mathbb{P}(\{\pi^{-1}(\sigma) \cap \text{correct}\})}{\mathbb{P}(\{\pi^{-1}(\sigma)\})}$$

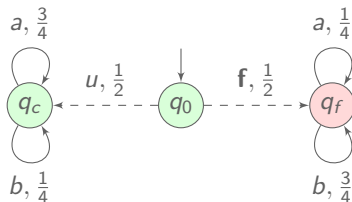


$$\text{CorP}(a) = 3/4, \text{CorP}(ab) = 1/2,$$

Proportion of Correct Runs

Given an observation sequence $\sigma \in \Sigma_o^*$,

$$\text{CorP}(\sigma) = \frac{\mathbb{P}(\{\pi^{-1}(\sigma) \cap \text{correct}\})}{\mathbb{P}(\{\pi^{-1}(\sigma)\})}$$



$\text{CorP}(a) = 3/4$, $\text{CorP}(ab) = 1/2$, $\text{CorP}(abb) = 1/4$, $\text{CorP}(abbb) = 1/10$.

Relaxing Soundness

Given $\varepsilon \geq 0$, an ε -diagnoser fulfills

- ▶ **Soundness:** If a fault is claimed after an observation sequence σ , then $\text{CorP}(\sigma) \leq \varepsilon$.

Relaxing Soundness

Given $\varepsilon \geq 0$, an ε -*diagnoser* fulfills

- ▶ **Soundness:** If a fault is claimed after an observation sequence σ , then $\text{CorP}(\sigma) \leq \varepsilon$.
- ▶ **Reactivity:** Given a faulty run ρ , the measure of undetected runs extending ρ converges to 0.

Relaxing Soundness

Given $\varepsilon \geq 0$, an ε -diagnoser fulfills

- ▶ **Soundness:** If a fault is claimed after an observation sequence σ , then $\text{CorP}(\sigma) \leq \varepsilon$.
- ▶ **Reactivity:** Given a faulty run ρ , the measure of undetected runs extending ρ converges to 0.

A *uniform* ε -diagnoser ensures for reactivity a uniform convergence over the faulty runs.

Relaxing Soundness

Given $\varepsilon \geq 0$, an ε -diagnoser fulfills

- ▶ **Soundness:** If a fault is claimed after an observation sequence σ , then $\text{CorP}(\sigma) \leq \varepsilon$.
- ▶ **Reactivity:** Given a faulty run ρ , the measure of undetected runs extending ρ converges to 0.

A *uniform* ε -diagnoser ensures for reactivity a uniform convergence over the faulty runs.

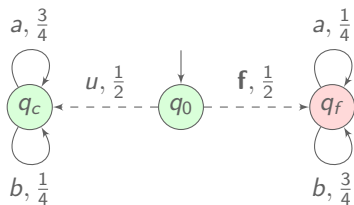
0-diagnosers correspond to exact diagnosers.

Approximate Diagnosis Problems

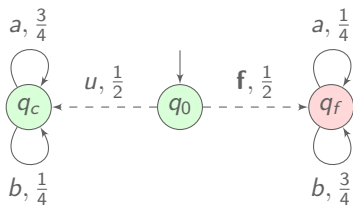
	Reactivity	
Accuracy	<p><i>ε-diagnosability</i></p> <p>Given $\varepsilon > 0$, does there exist an ε-diagnoser?</p>	<p><i>uniform ε-diagnosability</i></p> <p>Given $\varepsilon > 0$, does there exist a uniform ε-diagnoser?</p>
	<p><i>AA-diagnosability</i></p> <p>For all $\varepsilon > 0$, does there exist an ε-diagnoser?</p>	<p><i>uniform AA-diagnosability</i></p> <p>For all $\varepsilon > 0$, does there exist a uniform ε-diagnoser?</p>

AA-diagnosability allows to select ε depending on external requirements.

Illustration



Illustration

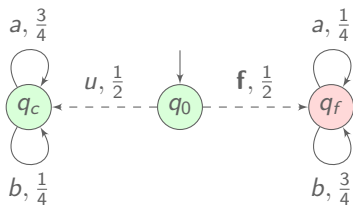


- **AA-diagnosable**

Let $\rho = q_0 \xrightarrow{f} q_f \cdots q_f$. Let ρ_f extending ρ .

Almost surely, when $|\rho_f| \rightarrow \infty$, ρ_f has more b 's than a 's.

Illustration



- **AA-diagnosable**

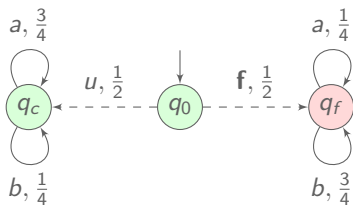
Let $\rho = q_0 \xrightarrow{f} q_f \cdots q_f$. Let ρ_f extending ρ .

Almost surely, when $|\rho_f| \rightarrow \infty$, ρ_f has more b 's than a 's.

Let ρ_c the correct run with $\mathcal{P}(\rho_f) = \mathcal{P}(\rho_c)$.

Almost surely, when $|\rho_c| \rightarrow \infty$, ρ_c has less b 's than a 's.

Illustration



- **AA-diagnosable**

Let $\rho = q_0 \xrightarrow{f} q_f \cdots q_f$. Let ρ_f extending ρ .

Almost surely, when $|\rho_f| \rightarrow \infty$, ρ_f has more b 's than a 's.

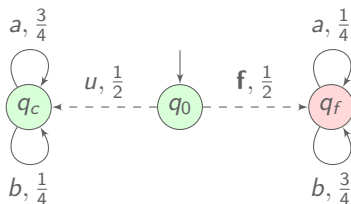
Let ρ_c the correct run with $\mathcal{P}(\rho_f) = \mathcal{P}(\rho_c)$.

Almost surely, when $|\rho_c| \rightarrow \infty$, ρ_c has less b 's than a 's.

- **Not uniformly AA-diagnosable**

Let $\varepsilon = \frac{1}{2}$, $\alpha > 0$ and ρ be the faulty run with $\mathcal{P}(\rho) = a^n$.

Illustration



- **AA-diagnosable**

Let $\rho = q_0 \xrightarrow{f} q_f \cdots q_f$. Let ρ_f extending ρ .

Almost surely, when $|\rho_f| \rightarrow \infty$, ρ_f has more b 's than a 's.

Let ρ_c the correct run with $\mathcal{P}(\rho_f) = \mathcal{P}(\rho_c)$.

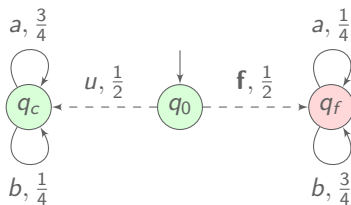
Almost surely, when $|\rho_c| \rightarrow \infty$, ρ_c has less b 's than a 's.

- **Not uniformly AA-diagnosable**

Let $\varepsilon = \frac{1}{2}$, $\alpha > 0$ and ρ be the faulty run with $\mathcal{P}(\rho) = a^n$.

Then for all ρ_f extending ρ with $|\rho_f| \leq n + |\rho|$, $\text{CorP}(\mathcal{P}(\rho)) \geq \frac{1}{2}$.

Illustration



- **AA-diagnosable**

Let $\rho = q_0 \xrightarrow{f} q_f \cdots q_f$. Let ρ_f extending ρ .

Almost surely, when $|\rho_f| \rightarrow \infty$, ρ_f has more b 's than a 's.

Let ρ_c the correct run with $\mathcal{P}(\rho_f) = \mathcal{P}(\rho_c)$.

Almost surely, when $|\rho_c| \rightarrow \infty$, ρ_c has less b 's than a 's.

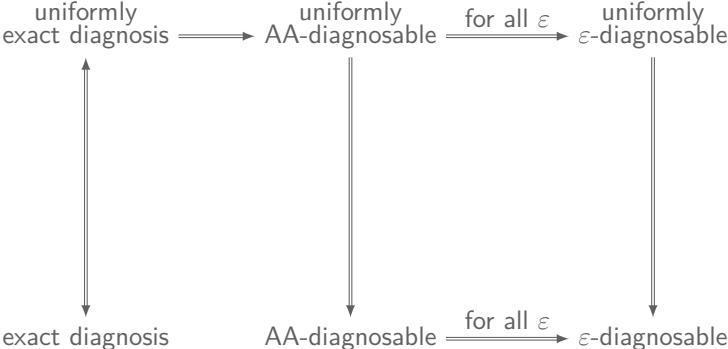
- **Not uniformly AA-diagnosable**

Let $\varepsilon = \frac{1}{2}$, $\alpha > 0$ and ρ be the faulty run with $\mathcal{P}(\rho) = a^n$.

Then for all ρ_f extending ρ with $|\rho_f| \leq n + |\rho|$, $\text{CorP}(\mathcal{P}(\rho)) \geq \frac{1}{2}$.

$\mathbb{P}(\rho_f | \rho \leq \rho_f \wedge |\rho_f| = k + |\rho| \wedge \text{CorP}(\mathcal{P}(\rho_f)) \leq \varepsilon) \leq \alpha \mathbb{P}(\rho)$ implies $k \geq n$.

Establishing relations between the Specifications



Complexity of the Problems

	Simple	Uniform
ε -diagnosability	undecidable	undecidable
AA-diagnosability	PTIME	undecidable

Outline

Specification of Approximate Diagnosis

AA-diagnosis is Easy

Other Approximate Diagnoses are Hard

A Simple Case

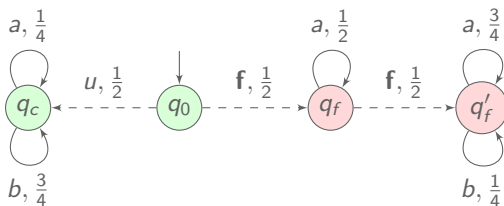
Initial fault pLTS. Initially, an unobservable split towards two subpLTS:

- ▶ a *correct* event u leads to a *correct* subpLTS;
- ▶ a *faulty* event \mathbf{f} leads to an *arbitrary* subpLTS.

A Simple Case

Initial fault pLTS. Initially, an unobservable split towards two subpLTS:

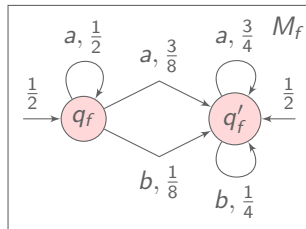
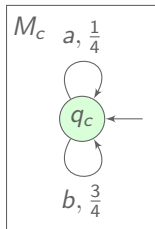
- ▶ a *correct* event u leads to a *correct* subpLTS;
- ▶ a *faulty* event f leads to an *arbitrary* subpLTS.



- ▶ an initial state, q_0 ;
- ▶ an arbitrary pLTS with states $\{q_f, q'_f\}$;
- ▶ a correct pLTS with state q_c .

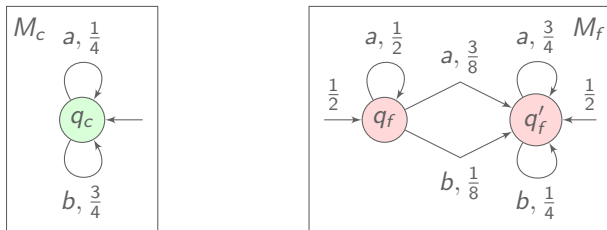
Solving AA-diagnosability for Initial-Fault pLTS

- Transform the correct and arbitrary subpLTS in *labelled Markov chains* by merging the unobservable transitions.



Solving AA-diagnosability for Initial-Fault pLTS

- Transform the correct and arbitrary subpLTS in *labelled Markov chains* by merging the unobservable transitions.



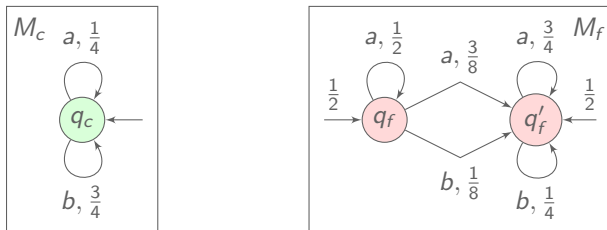
- $\mathbb{P}^M(E)$ = measure of infinite runs of M with observation in E .
Distance 1 problem: $\exists E$ (measurable) $\subseteq \Sigma_o^\omega$, $\mathbb{P}^{M_c}(E) - \mathbb{P}^{M_f}(E) = 1$?
- Illustration: $E = \{\sigma \mid \limsup_{n \rightarrow \infty} \frac{|\sigma_{\downarrow n}|_b}{|\sigma_{\downarrow n}|_a} > 1\}$

[CK14] Chen and Kiefer

On the Total Variation Distance of Labelled Markov Chains, CSL-LICS'14.

Solving AA-diagnosability for Initial-Fault pLTS

- Transform the correct and arbitrary subpLTS in *labelled Markov chains* by merging the unobservable transitions.



- $\mathbb{P}^M(E)$ = measure of infinite runs of M with observation in E .
Distance 1 problem: $\exists E$ (measurable) $\subseteq \Sigma_\omega^\omega, \mathbb{P}^{M_c}(E) - \mathbb{P}^{M_f}(E) = 1$?
- Illustration: $E = \{\sigma \mid \limsup_{n \rightarrow \infty} \frac{|\sigma_{\downarrow n}|_b}{|\sigma_{\downarrow n}|_a} > 1\}$

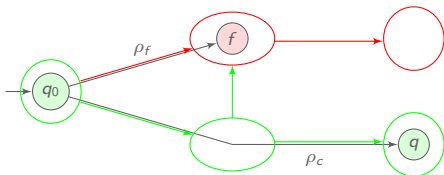
The distance 1 problem is decidable in PTIME.

[CK14] Chen and Kiefer

On the Total Variation Distance of Labelled Markov Chains, CSL-LICS'14.

Solving AA-diagnosability

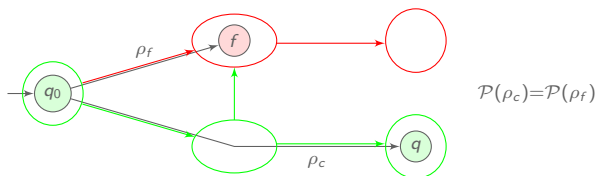
- Identifying relevant pairs of states by reachability analysis in the synchronised self-product.



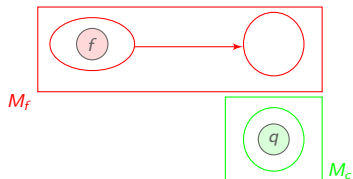
$$\mathcal{P}(\rho_c) = \mathcal{P}(\rho_f)$$

Solving AA-diagnosability

- Identifying relevant pairs of states by reachability analysis in the synchronised self-product.

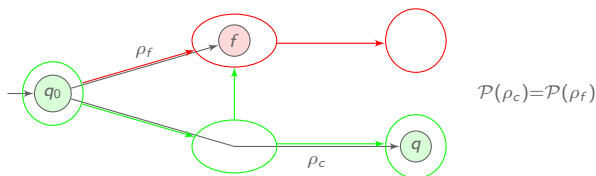


- Checking distance 1 for all relevant pairs.

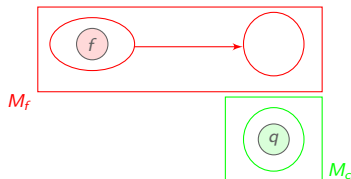


Solving AA-diagnosability

- Identifying relevant pairs of states by reachability analysis in the synchronised self-product.



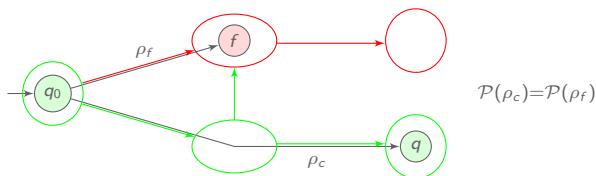
- Checking distance 1 for all relevant pairs.



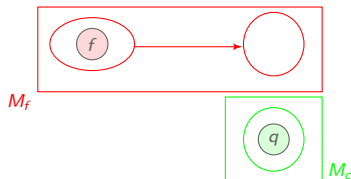
AA-diagnosability is decidable in PTIME.

Solving AA-diagnosability

- Identifying relevant pairs of states by reachability analysis in the synchronised self-product.



- Checking distance 1 for all relevant pairs.



AA-diagnosability is decidable in PTIME.

However an ε -diagnoser may need infinite memory.

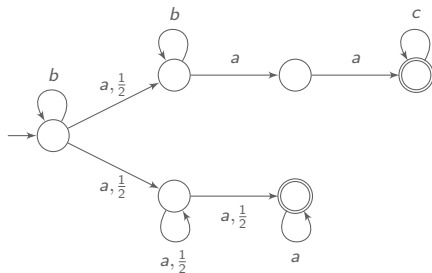
Outline

Specification of Approximate Diagnosis

AA-diagnosis is Easy

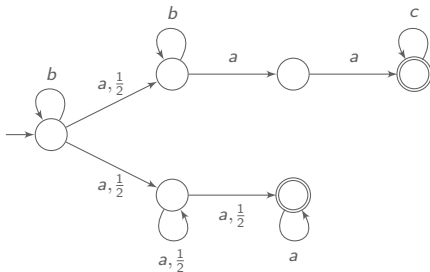
Other Approximate Diagnoses are Hard

The Emptiness Problem for Probabilistic Automata (PA)



$$\mathbb{P}(b) = 0, \mathbb{P}(baa) = \frac{1}{4}, \mathbb{P}(baaa) = \frac{7}{8}$$

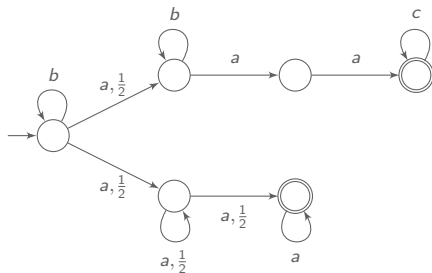
The Emptiness Problem for Probabilistic Automata (PA)



$$\mathbb{P}(b) = 0, \mathbb{P}(baa) = \frac{1}{4}, \mathbb{P}(baaa) = \frac{7}{8}$$

Emptiness problem: Given a PA \mathcal{A} ,
 $\exists w \in \Sigma^*, \mathbb{P}_{\mathcal{A}}(w) > \frac{1}{2}$?

The Emptiness Problem for Probabilistic Automata (PA)



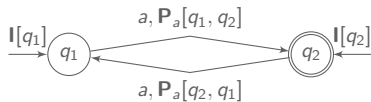
$$\mathbb{P}(b) = 0, \mathbb{P}(baa) = \frac{1}{4}, \mathbb{P}(baaa) = \frac{7}{8}$$

Emptiness problem: Given a PA \mathcal{A} ,
 $\exists w \in \Sigma^*, \mathbb{P}_{\mathcal{A}}(w) > \frac{1}{2}$?

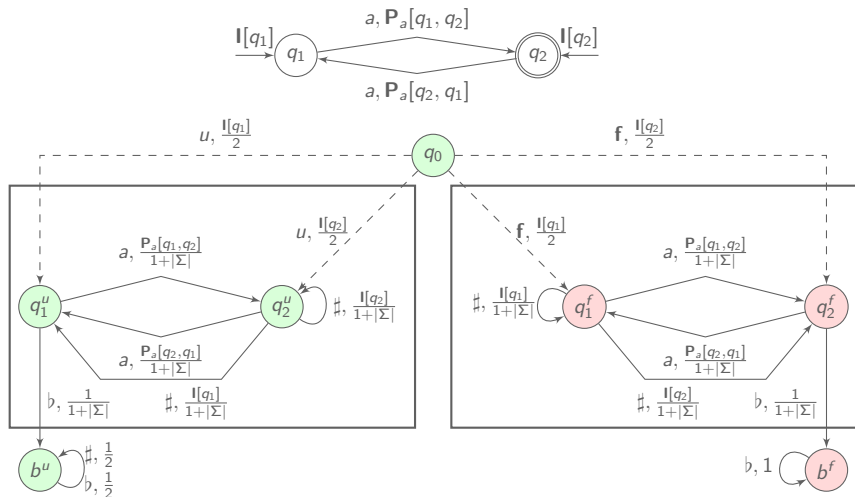
The emptiness problem for PA is undecidable even when for all w ,
 $\frac{1}{4} \leq \mathbb{P}_{\mathcal{A}}(w) \leq \frac{3}{4}$.

[P71] Paz, *Introduction to Probabilistic Automata*, Academic Press 1971.

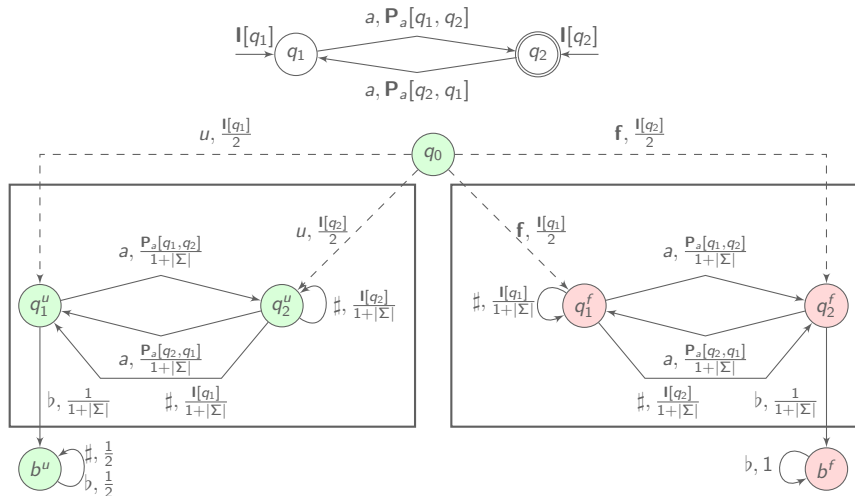
From PA to Uniform AA-diagnosability



From PA to Uniform AA-diagnosability

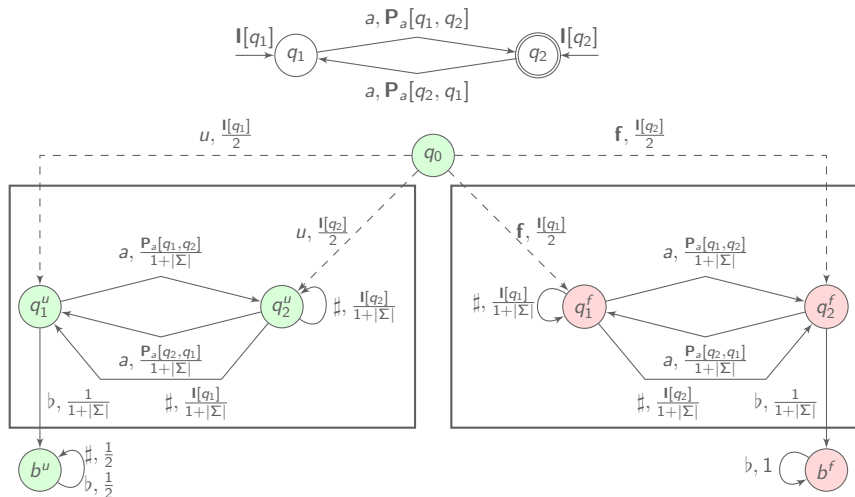


From PA to Uniform AA-diagnosability



If $\exists w \in \Sigma_o^*, \mathbb{P}_{\mathcal{A}}(w) > 1/2$ then $\lim_{n \rightarrow \infty} \text{CorP}((w\#)^n b) = 1$.

From PA to Uniform AA-diagnosability



If $\exists w \in \Sigma_o^*, \mathbb{P}_{\mathcal{A}}(w) > 1/2$ then $\lim_{n \rightarrow \infty} \text{CorP}((w\#)^n b) = 1$.

If $\forall w \in \Sigma_o^*, \mathbb{P}_{\mathcal{A}}(w) \leq 1/2$ then $\forall n \text{ CorP}((w\#)^n b) \leq \frac{3}{4}$.

Conclusion

Contributions

- ▶ Investigation of semantical issues
- ▶ Complexity of the notions of approximate diagnosis
 - ▶ A PTIME algorithm for AA-diagnosability
 - ▶ Undecidability of other approximate diagnosability

Conclusion

Contributions

- ▶ Investigation of semantical issues
- ▶ Complexity of the notions of approximate diagnosis
 - ▶ A PTIME algorithm for AA-diagnosability
 - ▶ Undecidability of other approximate diagnosability

Future work

- ▶ Approximate prediction and prediagnosis
- ▶ Diagnosis of infinite state stochastic systems